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1     **VARIABLE GEOMETRY WORKTABLE**

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3     The present invention relates to worktables and more particularly to portable  
4     worktables with clamping/displacement means wherein it is provided that the  
5     working height, the ground-angle-working-plane and the maximum-operational-  
6     footprint may be varied.

7     The original Black & Decker Workmate could be used at three heights: folded  
8     on the ground, at fully opened position or at a mid-way point where the short  
9     base legs are folded underneath the main structure of the worktable.

10    Also known are clamping tables in which the worktop may be pivoted to an  
11    angle to the horizontal without changing the geometric angle configuration of the  
12    basic leg support. Such angled worktops may serve a limited function in holding  
13    a drawing board or canvas for a painting for example but are essentially  
14    unsuitable in angled plane for any woodworking operation.

15    Also known are clamping tables in which there is a tightening jaw and a fixed  
16    jaw in which the fixed jaw may be fitted at several points on the top frame.  
17    Clearly at each point the maximum opening capacity of the jaws is varied but  
18    the maximum-operational- footprint for the jaws is not : it remains always at the  
19    furthest fixing point for the fixed jaw relative to the tightening jaw. Extensions to  
20    the worktop of such clamping tables are also known, normally in the form of clip  
21    on trays on which tools may be placed but these do not increase the maximum-  
22    operational-footprint of the clamping /displacement means.

23    In the light of this known art the new provisions of the present invention may  
24    now be described and clearly defined.

25    The primary aim of this invention is to provide a compact  
26    clamping/displacement worktable system wherein the maximum capacity to  
27    hold a workpiece may be varied by varying the geometrical configuration of the  
28    worktable structure such that in standard mode, for example, it may be suited to  
29    holding a small to medium sized workpiece and in extended mode may be  
30    doubled in capacity to hold a door, for example.

31    In the terms of this invention "clamping/displacement worktable" means a

worktable having means for displacing one worktop section relative to another wherein these worktop sections are operatively cooperative, for example, two worktop sections as the jaws of a clamp tightened together to hold a workpiece or, for another example, a worktop section with attached fence guide displaceably adjustable with a worktop section holding a circular saw for purposes of determining the width of saw cut.

In the terms of this invention "worktop section" means the primary supporting structure for workpieces and tools : it does not include any element placed on or attached to the surface of the said worktop section and dependent on it for support. A worktop section would normally, but not necessarily, have a planar surface : for example a round section tube fixed at each end to a worktop section mount, the said tube spanning the worktable to support a workpiece or tool would in the terms of this invention be defined as a "worktop section" and even a simple block each side of the table at worktop section height without any spanning of the table would, in terms of its function of supporting a workpiece at worktop section height, be considered a worktop section.

In the terms of this invention "maximum-operational-footprint" means the maximum area over which two or more operationally cooperative worktop sections may function given any mode or geometric configuration for the leg support and top frame support structure.

The secondary aim of this invention is to provide a working plane for two or more operationally cooperative worktop sections, the said plane being set at one or more angles to the ground. the operational footprint of the said worktop sections starting, at the control end of the worktable, at more or less normal working height and extending down towards the ground. This angled working plane is extremely useful in, for example, the circular sawing of thick planks where the line of the force involved in the operation is directed towards the ground eliminating any possibility of the worktable moving away from the said force.

In the terms of this invention a "ground-angle-working-plane" is a plane wherein the worktop sections may be angled in a line from normal working height towards the ground and wherein the top frame and top frame extension extend in parallel angled line to the ground to provide stable support and if required extension to ground level of the maximum-operational-footprint of the said worktop sections.

The Variable Geometry Worktable described in this invention may simultaneously provide the three requirements of : variable working height, variable maximum-operational-footprint and variable ground-angle-working-plane. All three of the said requirements are achieved essentially by releasing the folding leg support structure from a singly determined linked relationship or put in another way ....providing the means whereby the distance between two directly-linked, cooperatively-articulating axis points on a folding leg support structure may be varied either by releasing the link or by adjusting its length. "Directly-linked" in the terms of this invention means that there are no

1 intermediate cooperatively articulating axis points;  
2 Embodiments of the invention will now be described, by way of example only,  
3 with reference to the accompanying drawings, in which  
4 **FIG. 1** is a side view of a Variable Geometry Worktable ( VGW) in folded  
5 position;  
6 **FIG.2** is a side view of the same VGW in open, normal-working-  
7 position;  
8 **FIG.3** is a side view of the same VGW in ground-angle-working-plane;  
9 **FIG.4** is a side view of the same VGW set in a higher, steeper ground-angle-  
10 working-plane;  
11 **FIG.5** is a side view of the same VGW set in the same angle-plane as in FIG.4  
12 but with an operational-footprint for the worktop sections extending almost to  
13 the ground;  
14 **FIG.6** is a side view of the same VGW with the original leg supports set at the  
15 same angle to each other as in FIG.3 but with an additional extension-leg  
16 support holding the original folded leg support in an extended horizontal plane;  
17 **FIG.7** is a side view of the same VGW set in similar configuration as in FIG.6  
18 but disposing a tool plate in the middle and a fence guide attached to a worktop  
19 section to the right;  
20 **FIGS. 8 & 9** are side views of the control layout at the axis point for the control-  
21 end and far-end leg supports respectively;  
22 **FIG.10** is a schematic end view of the leg lock bolt at the control-end of the  
23 VGW;  
24 **FIG.11** is a schematic cross-section view showing the positioning and  
25 interlocking mechanism on the worktop section mount which attaches it to the  
26 clamping plate shown in FIG.13;  
27 **FIG.12** is a three-dimensional sketch of the toothed interlocking element shown  
28 in FIG.11;  
29 **FIG.13** is a three-dimensional sketch of the clamping plate to which the  
30 interlocking elements shown in FIGS. 11&12 attach themselves;  
31 **FIG. 14** is a schematic, cross-section view of the top frame aliner with slider  
32 attached to the folded far-end leg support;  
33 **FIG. 15** is a schematic side view of the point at which the top frame aliner is  
34 linked to the clamping plate under the top frame.  
35 **FIG. 16** is a side view of the VGW with telescopic strut support linking the leg  
36 supports;  
37 **FIG. 17** is a partial view of a telescopic top frame support;  
38 **FIG. 18** is a side schematic view of a strut lock.  
39 Referring to **FIGS 1&2** the folded and open, normal-working-position  
40 respectively in the preferred forms of the invention, a  
41 Variable Geometry Worktable ( VGW ) comprises a top frame 1  
42 under which both control-end leg support 2 and far-end leg support 3 fold in  
43 parallel alignment, the control-end leg support resting under the far-end leg

1 support ,the two legs supports being joined in both folded and normal-working-  
2 position by a strut 4 ,  
3 at the end of each leg support there being a foot 5 suitable in shape for variable  
4 positioning and fixed to the top frame at the control -end a worktop section  
5 mount 6 to which is attached a worktop section 7 and at the far-end a worktop  
6 section mount 8 selectively displaceable along the top frame together with its  
7 attached worktop section 9, a control button 10 locking it when required to a  
8 clamping/displacement means operated by winding handle 11 at the control-  
9 end and a rondel 12 at each end masking the control elements for keeping the  
10 leg supports in rigid open position.  
11 In FIG.3 the VGW is shown in a ground-angle-working-plane the control-end  
12 legs being still locked in the same angle relative to the top frame as shown in  
13 FIG.2 opening of the strut on the control-end leg support permitting the far-end  
14 leg support to be released and simultaneously placed parallel with the top  
15 frame in folded position  
16 the VGW in this configuration providing a much lower working height suitable for  
17 example for sawing a log wherein the displaceable worktop section in the mode  
18 of tightening jaw may hold the workpiece W helped by clamping blocks 13  
19 attached to the worktop section surface the arrow F showing the position for the  
20 feet to be placed on a ground level cross-piece tube 14 joining far-end leg  
21 supports the arrow T indicating the action direction of the tool in this case a hand  
22 saw.  
23 In FIG.4 the VGW is shown in another ground-angle-working-plane the far-end  
24 leg support still in fully folded position relative to the top frame but the control-  
25 end leg support is locked in a slightly more closed position resulting in an initially  
26 higher or more normal working height and a steeper ground-angle-working-plane  
27 suitable for example for circular saw cross-cutting of thick planks the foot being in  
28 this case placed on the tubular ground level cross piece of the control-end leg  
29 supports the action direction of the tool in this case a circular saw being in a steep  
30 line to the ground preventing the VGW from moving away from the power tool  
31 pressure. It should be noted that in going from normal folded position as in  
32 FIG.1 to normal-working-position as in FIG.2 the leg supports go through many  
33 angle changes relative to the top frame and to each other as they do in most  
34 folding worktables the relevance of the VGW system being that it separates  
35 where necessary the link between control-end and far-end leg support and that it  
36 locks the angle between them at specific useful working configurations or in the  
37 terms of this invention at " operational angles " between the leg supports.  
38 In FIG. 5 the VGW is shown in the same ground-angle-working-plane as in  
39 FIG.4 but an extension clamping bar 15 attached at one end to the inside face of  
40 displaceable or tightenable worktop section mount is supported at the distal  
41 end by a slider support 16 which is attached to and may slide along the far-end  
42 leg support which in this configuration serves a dual function of leg support and  
43 top frame extension support, an extension bar block 17 which may support a

workpiece at the level of worktop sections 7&9 and in the terms of this invention itself considered a worktop section is selectively positionable along the extension bar, activation of the clamping/displacement means situated on the original top frame support 1 tightening worktop section mount 8 towards the fixed worktop section 7 but equally tightening worktop section 17 towards worktop section 7 effectively increasing the maximum-operational-footprint of the VGW in this configuration by a factor of 2 relative to the normal-working-position. The workpiece W shown here by way of example is a door and the direction action shown for the tool T is that for a drill to drill a slot for the fixing of a lock

In FIG. 6 the control-end and far-end leg supports have been set in the operational-angle shown in FIG.3 but an extension leg support 18 holds the far-end leg support 3 in a horizontal plane connecting with the foot of leg support 3 by means of linking element 19 and being also held by the distal end of strut 4 still attached at its axis to the far-end leg support which in this configuration of the VGW no longer serves in the mode of leg support but only in the mode of top frame extension support.

A preferred system of increasing maximum-operational-footprint to that described in FIG.5 is here shown in FIG.6 a top frame aligner 20 reproducing the essential form and feature characteristics of the original top frame support 1 and the essential form and feature characteristics of a displaceable clamping device mounted underneath the original top frame support the said top frame aligner being itself displaceable along the top frame extension support 3 by means of sliders 21 the feature characteristics of the top frame aligner permitting the displaceable worktop mount 8 to be selectively positioned and fixed along the length of the said top frame aligner in the same manner that it may be positioned and fixed along the length of the displaceable clamping device situated under the original top frame support the said top frame aligner also being linked to the displaceable clamping device under the original top frame support 1 may be tightened towards fixed worktop section 7.

In FIG. 7 the VGW is shown in a similar configuration to that of FIG. 6 but with the worktop sections no longer functioning as clamping jaw elements, instead another worktop section in the form of a tool plate 22 to which a power tool, for example a circular saw, may be attached from underneath is supported by a worktop section mount 23 which is set in fixed position on the top frame support 1 the displaceable worktop mount 8 carrying worktop section 9 to which a fence guide 25 has been attached the clamping/displacement means of the VGW adjusting the distance between saw blade 24 and fence guide 25

In FIG.8 is shown the control layout on the top frame support behind rondel 12 for the control-end leg support, the axis point for the said leg support with the top frame being situated at point 26 the said leg support 2 opening to a point where it is blocked by a bolt and square nut 27 & 28 respectively a spring loaded bolt on the said leg support engaging with the top frame support at

1 position 29 for the normal-working- position angle as shown in FIGS 2 and at  
2 position 30 for the operational angle for the control-end leg structure as shown in  
3 FIGS. 4 & 5 . The general provisions of the invention do not preclude other  
4 operational-angle positions or indeed other means , such as tightening means for  
5 locking the leg supports at a selected angle to the top frame.

6 In FIG. 9 is shown the control layout on the top frame behind rondel 12 for the  
7 far-end leg support the axis point for the said leg support being at a higher point  
8 31 than for the control-end leg but the opening of the far-end leg support is  
9 similarly blocked at a certain point by a bolt and square nut 27 & 28  
10 respectively. In normal-working-position the strut 4 holds the two legs together  
11 pulling the far-end leg support against its blocking nut 28 and pulling the control-  
12 end leg support back against its locking bolt 29a.

13 In FIG.10 is shown a partial end view of a VGW about the point of the control-  
14 end leg support axis in which a leg axis washer 32 lies between the said leg  
15 support 2 and top frame support 1 a top cross-piece 33 joining control-end leg  
16 supports at either side of the VGW the said cross-piece supporting a leg  
17 locking system at either end comprising a spring loaded bolt 29a which is  
18 activated by a handle 34 which when turned towards the leg support around an  
19 axis 34a pulls the leg locking bolt out of its locating hole 29 in the top frame  
20 releasing the leg support to be repositioned at another angle locating point in the  
21 top frame, for example 30 or to be fully folded. The position of the leg axis bolt  
22 26a which joins the leg support to the top frame is also indicated. An element 35  
23 is inserted into the end of the top frame support primarily to hold the clamping  
24 means ( the clamping handle which would normally be fitted at this point not  
25 being shown ), the flat underside of a similar said element 35 positioned at the  
26 far-end of the top frame support precisely blocking the folded position alignment  
27 of the far-end leg support parallel to the top frame support.

28 In FIG. 11 is shown a quick-fit / quick-release system for positioning a  
29 displaceable worktop mount 8 comprising a control bolt 10 with spring return  
30 10a, fitted at the distal by the means of two nuts 10b a toothed section 36  
31 which interlocks with a toothed section 37a on a displaceable clamping plate 37  
32 and a retention plate 36a which fits under the clamping plate 37 the said  
33 clamping plate being displaced by a tightening thread 38 which runs through it  
34 the said thread being turned by handle 11 at the control end of the VGW  
35 In FIG. 12 is shown the interlocking toothed element 36 and the retention plate  
36 36a. When the control bolt is pushed releasing the toothed interlocking section  
37 the retention plate still keeps the worktop mount firmly attached to the top frame  
38 support.

39 In FIG.13 is shown the displaceable clamping plate 37 with toothed section  
40 37a and two enfolded nuts 38a through which the tightening thread 38 may  
41 run. A slot 37b in the displaceable clamping plate provides a point to which a  
42 linked top frame aligner  
43 may be joined.

1 In **FIG. 14** is shown a cross-sectional view of the top frame aligner **20** mounted  
2 by means of a slider **21** onto the top frame extension support **3** the part **20a**  
3 marking a toothed profile on the top frame aligner and **39** marking the attachment  
4 point of an element which joins the top frame aligner with the displaceable  
5 clamping plate **37**.

6 In **FIG. 15** is shown from the inside face of the top frame support **1**  
7 and the inside face of the top frame aligner **20** the linking element  
8 **39** which attaches the top frame aligner with the slot in the displaceable clamping  
9 plate **37**.

10 **FIGS. 11-15** describe an embodiment of a clamping/displacement  
11 system which may be simply extended from a shorter maximum-operational-  
12 footprint for the worktop sections to an extended maximum-operational-footprint  
13 on a VGW. The very rapid adjustment of a tightening jaw is however useful  
14 even for conventional worktables. The principles of the system, which in the  
15 terms of this invention is called a " clamping/displacement override system " are  
16 as follows: the clamping/displacement means ( handle and tightening thread in  
17 the described embodiment ) activates a primary clamping/displacement vehicle  
18 ( clamping plate ) along which a secondary clamping/displacement vehicle (   
19 displaceable worktop section mount ) may be selectively positioned and fixed,  
20 the secondary clamping displacement vehicle being employed to displace the  
21 worktop section over a larger distance along the length of the primary vehicle  
22 and any extension linked to it ( top frame aligner) to a selected fixing point on the  
23 said primary vehicle or extension linked to it, the primary vehicle being  
24 employed to tighten and/or displacementally adjust the secondary vehicle with  
25 any attached worktop section over the remaining smaller distance. It should be  
26 noted in FIG. 5 element **17** is a tertiary clamping displacement vehicle  
27 displaceable along the extension **15** of the secondary vehicle, the displaceable  
28 worktop section mount **8**.

29 In **FIG. 16** is shown a telescopic strut **4** joining leg supports **2&3** a  
30 telescopically extendable portion **4a** locked into position by tightening means  
31 **4b** permits the distance between the directly-  
32 linked, cooperatively-articulating strut axis points **2a & 3a** to be varied while at  
33 the same time still remaining linked. The general provisions of the invention do  
34 not exclude other ways in which the distance between the strut axis points on  
35 the leg supports may be varied but linked.

36 In **FIG. 17** is shown an alternative embodiment for varying the maximum-  
37 operational-footprint for the worktop sections in which the top frame support **1**  
38 has a telescopic extendable section **1a** with fitting points **1b** for the attachment  
39 at variable points of a fixed worktop section, the leg axis point **3b** of the far-end  
40 leg **3** may be extended away from the leg axis point of the control-end leg  
41 support the adjustable length top frame being the direct-link between the two  
42 operatively articulating leg axis points. In this embodiment the control-end leg  
43 supports may rest in a more or less vertical open position and the far-end leg

1       supprt may be folded inwards the extended top frame being angled down to  
2       the ground so that element 40 on the top of leg support 3 becomes the foot of  
3       the far-end leg support when the said support is in folded position . in this  
4       embodiment the tightening/ displaceable worktop section is situated at the  
5       control end of the VGW.  
6       In **FIG. 18** is shown the locked and open position 41 & 42 respectively of a  
7       strut lock which may act as a quick-fit/quick-release system for the attachment of a  
8       strut to a leg support. The strut position here shown is that of FIGS 6 & 7 where  
9       the strut joins in upside down position the extension leg support 18 the strut lock  
10      is spring loaded in locked position so the strut is not free to fall away from its  
11      attachment point